# Proportional pressure reducing valves type PM and PMZ

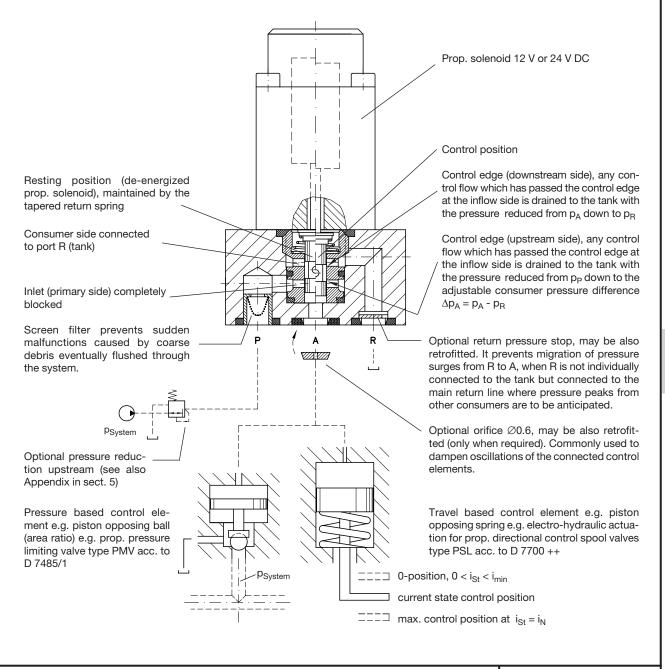
preferably as pilot valve up to approx. 30 bar

Pressure difference  $\Delta p_{max} = 30 \text{ bar}$ Flow  $Q_{max} = 2 \text{ lpm}$ 

## 1. General

The pressure reducing valves type PM and PMZ are directly actuated valves in all-steel design. They consist of valve body, controller spool and -sleeve, and prop. actuation solenoid. The higher, eventually varying system pressure  $p_p$  apparent at port P is reduced down to a lower constant pressure level at port A. This pressure level corresponds to the current fed to the prop. solenoid with a limit  $\Delta p_A = p_A - p_B$ . The pressure  $p_A$  apparent at port A is used for hydraulic actuators or for stepless switching operations at variable displacement pumps, proportional valves etc. The power consumption of the prop. solenoid is low, enabling use of prop. amplifiers type EV acc. to D 7817/1, D 7831/1, D 7831 D or D 7835 as well as the programmable logic valve control type PLVC acc. to D 7845 ++.

The max. inlet (system) pressure at port P is rated at 40 bar to prevent any controller inaccuracies or stepwise operation after steady-state periods. When the system pressure is higher than 40 bar it is recommended to use a pressure reducing valve e.g. type ADC 1-25 or AM 1-25 acc. to D 7458, see also examples in sect. 5.



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Prop. pressure reducing valve PM(Z)

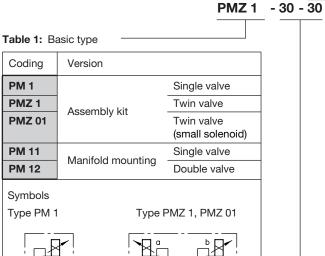
# 2. Available versions, main data2.1 Individual valves

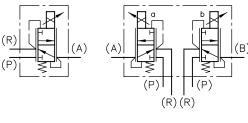
PM 11 - 7 - B 0,6 - G 24 /1

- G 24

- 1/4

# 2.1 Individual valves Order example:





Type PM 11

Type PM 12

A

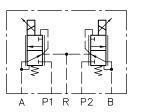
A

R

P

Type PMZ 1.. - 1/4

Table 4: Nom. solenoid voltage



Individual connection block, port G 1/4 (BSPP) (for type PMZ 1 only)

Assembly kits PM 1 and PMZ 1
Without coding = Individual parts

Single and double valves PM 11 and PM 12 /1 (/2, /3) = Solenoid orientation (see sect. 4.2)

Table 3: Additional elements

Solenoid orientation

Coding	Description	
(ohne)	Standard	
R	Return pressure stop at R	
В 0,6	Throttle Ø0.6 at A and B	and PM 12

**Table 2:** Proportionally adjustable nominal pressure difference

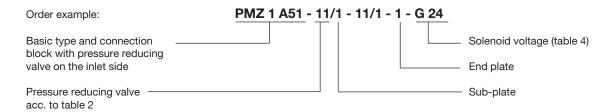
Coding	$\Delta p_A = p_A - p_R$ (bar)				
30	30				
19	19				
14	14				
11	11.5				
9	9				
7	7.5				
5,5	5.5				
4	4.5				

- 1) Not available as valve bank
- 2) Options ...T and ...TH only available with type PMZ 1 and PMZ 01

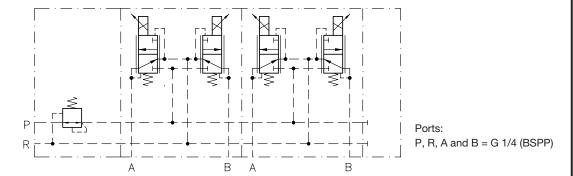
Coding		Nominal	Description			
Coung		voltage	Description		PMZ 1	PMZ 01
G 12, G 12 T(H) <sup>2</sup> )	X 12, X 12 T(H) <sup>2</sup> )	12 V DC	Standard, version with connection conf. EN 175 301-803 with (G) or without (X) plug			
G 24, G 24 T(H) <sup>2</sup> )	X 24, X 24 T(H) <sup>2</sup> )	24 V DC	G(X)T with manual emergency actuation, G(X)TH with additional push button			
G 24 H 4	X 24 H 4	24 V DC	Like G 24 (X 24), but solenoid for electrical actuation 4-pin		•	
G 24 C 4	X 24 C 4	24 V DC	Version with connection conf. EN 175 301-803, 4-pin, with (G) or without (X) plug		•	
AMP 24 H 4		24 V DC	Version with connection via AMP Junior Timer, 4-pin at electrical actuation		•	•
DT 12 DT 24		12 V DC 24 V DC	Connection via plug Co. DEUTSCH DT 04-4P, suited for socket DT 06-4S		•	•
<b>S 12, S 12 T</b> <sup>2</sup> ) 12 V DC		12 V DC	Version with quarter turn type plug (Bayonet PA 6, Co. Schlemmer D-85586		_	
S 24, S 24 T	Poing, suited for taper with bayonet 10 SL), version ST with additional manual emergency actuation. Plug is not scope of delivery.		•	•	•	
G 24 EX G 24 EX-10	For use in areas with explosion hazardous atmosphere. Suited for category 2 and 3, zone 1, 21, 2, 22.  Protection class EEx m II 120° (T4), with cable length 3 m (no coding) or 10 m			•		
G 24 MSHA G 24 MSHA	/ 124 V.D.C. I (China) approval is mandatory. Protection class I M2 Ev. d I (flame proof I			•		

## 2.2 Valve bank

It is possible to arrange the individual valves type as valve banks via sub-plates. A maximum of 10 valves can be combined. **Attention:** Not available are valves with ex-proof solenoids!



Symbol



## 3. Additional parameters

## 3.1 General and hydraulic

Nomenclature, design Proportional pressure reducing valve; directly actuated spool type valve with additional safety

valve function (conf. DIN ISO 1219-1)

Material All-steel design; controller sleeve nitrous hardened and honed. Controller spool hardened and

ground. Both components polish-deburred. Optimum wear resistance against erosion and cavitation

caused by the passing fluid.

Surface treatment Valve body: gal Zn 5-8bk

Proportional solenoid: gal Zn 12mtcD

Port coding P = Inlet (primary side)

A = Consumer outlet (secondary side)

R = Return (to the tank)

Pipe connection PM 1, PMZ 1: Corresponding ports are to be located in the customer furnished manifold.

Attention: Provide a contamination screen at the P-side, e.g. type HFC 1/4 F

acc. to D 7235

PM 11, PM 12,

PMZ 1..-1/4: For dimensions, see sect. 4.3

Installed position Any

Flow direction  $P \rightarrow A (\rightarrow R)$  (Controller position at fluid removal mode)

 $A \rightarrow R$  (Controller position at safety valve function mode)

Operating pressure Inlet P (P1, P2): p<sub>P max</sub> = 40 bar, when the system pressure is higher a pressure reducing valve should

be provided e.g. type ADC 1 or AM 1 acc. to D 7458, see also examples in sect. 5.

Outlet A (B):  $p_A = \Delta p_A + p_R$ 

proportionally adjustable pressure difference  $\Delta p_A = (0) \dots 4$  to  $(0) \dots 30$  bar

dep. on type, see also curves at page 4

Outlet R: best depressurized to the tank,  $p_R \le 20$  bar with PM 1, PM 11, PM 12

 $p_R < 5$  bar with PMZ 1

permissible static load capacity (idle mode) PM 1, PM 11, PM 12 = 315 bar (all ports)

PMZ 1: P (P1, P2) = 40 bar; A (B) = 20 bar; R = 5 bar

Flow Q<sub>max</sub> approx. 2 lpm

Mass (weight) PM 1 = 200 g; PM 11 = 300 g; PM 12 = 600 g; PMZ 1 = 500 g; PMZ 1...-1/4 = 600 g

Pressure fluid Hydraulic oil acc. to DIN 51524 table 1 to 3; ISO VG 10 to 68 conf. DIN 51 519

Viscosity range: min. approx. 4; max. approx. 600 mm<sup>2</sup>/sec

Optimum: 10 to 500 mm<sup>2</sup>/sec

Also suitable are biologically degradable pressure fluids type HEES (synth. Ester) at operation

temperatures up to approx. +70°C.

Temperature Ambient: approx. -40...+80°C

Fluid: -25...+80°C, pay attention to the viscosity range!

Start temperature down to -40°C are allowable (Pay attention to the viscosity range during start!), as long as the operation temperature during subsequent running is at least 20K higher. Biological degradable pressure fluids: Pay attention to manufacturer's information. With regard to the

compatibility with sealing materials do not exceed +70°C.

Restriction regarding ex-proof solenoid

max. ambient temperature -35 ... +40°C, Fluid: max. 70°C

Notes regarding use Observe the operation manual B 01/2002!

of ex-proof solenoids: The assembly kit type PMZ 1 can only be used when a manifold with minimum dimension of

96 x 80 x 49.5 mm is provided.

It is therefore not possible to use ex-proof versions in valve banks type PMZ 1 A51-... acc. to sect. 2.2.

Both coils of the twin solenoid must not be energized simultaneously!

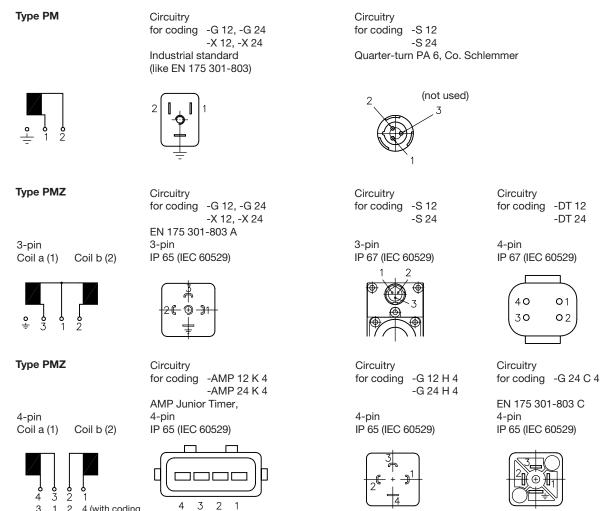
### 3.2 **Electrical data**

Solenoid		The armature connected to	•	wet armature so armature is mai		d to the outside and internally ubed by the hydraulic fluid and	
Valve type	PM			Z 01			
Nom. voltage U <sub>N</sub>	(V DC)	12	24	12	24	24 (ex-proof) ripple 15%	
Coil resistance R <sub>20</sub> ± 5%	(Ω)	5.9	24	6.7 / 6.7	27.2 / 28	27.0 /	
Current, cold I <sub>20</sub>	(A)	2.0	1.0	1.8 / 1.8	0.88 / 0.86	0.88 /	
Max. current I <sub>G</sub>	(A)	1.26	0.63	1.26 / 1.16	0.63 / 0.58	0.63 /	
Power, cold $P_{20} = U_N \times I_{20}$	(W)	24	24	22 / 22	21 / 21	21.5 /	
Max. power $P_G = U_N \times I_G$	(W)	9.5	9.5	10.6 / 13.9	10.8 / 13.9	10.8 /	
Switch-off energy W <sub>A</sub>	(Ws)	≤ 0.3	≤ 0.3	≤ 0.3	≤ 0.3	≤ 0.3	
Relative duty cycle		100%		100% ED (c	only one coil)		
Protection class X, G: IEC 70 (Co) 13 S:		IP 65 with properly mounted plug IP 67 (IEC 60529)			IP 67 (IEC 60529)		
Required dither frequency		50 150 Hz					
Dither amplitude							
$A_{D}(\%) = \frac{I_{peak - peak}}{I_{G}} \cdot 100$	20% ≤ A <sub>D</sub> ≤ 40%						

## Electr. connection

1 2 4 (with coding

...H 4 and ...C 4)



The IP-specification only applies when the plug is mounted as specified.

Additional notes regarding versions with ex-proof solenoid (see also restrictions at page 3!)

Letter of conformity

Coding

TÜV - A02 ATEX 0007 X

 $\ensuremath{\mbox{\ensuremath{\&}}}\xspace$  II 2 GD T120°C IP67 EEx m II 120°C(T4)

**Attention:** Additionally observe operating manuals B 01/2002 and B ATEX.

I<sub>F</sub> < 1.8 A medium

Protect against direct sun light (see also restrictions at "Temperature")

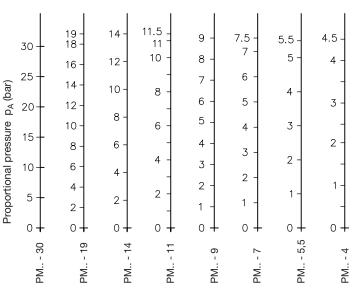
conforming EN 50014, DIN VDE 0170/0171 T1 and T9

Installation

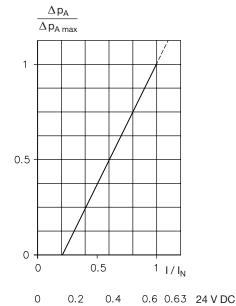
Required electrical fusing (acc. to IEC 127)

Electrical layout and testing

 $\Delta p_A$ -I-curves



Oil viscosity during measurement approx. 60 mm<sup>2</sup>/sec



Control current (A)

0.8 1 1.2 1.26

12 V DC

## 4. Unit dimensions All dimensions in mm, subject to change without notice!

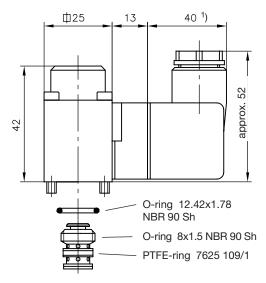
## 4.1 Assembly kits

## Individual valve type PM 1

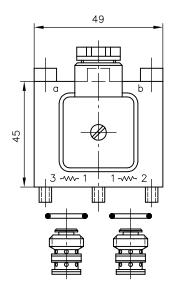
Solenoid coding G..

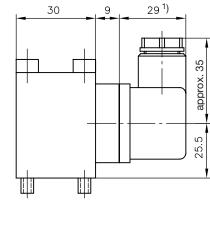
## Twin valve PMZ 1

Solenoid coding G..



Prop. pressure reducing valve insert





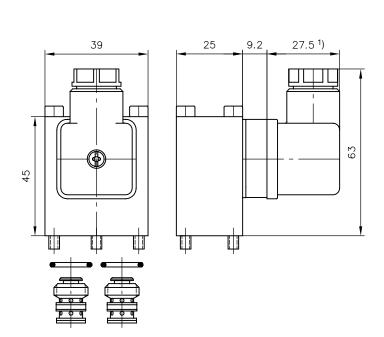
## Type PM

Solenoid coding S

# Quarter-turn PA 6 2)

## Twin valve type PMZ 01

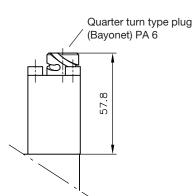
Solenoid coding G..



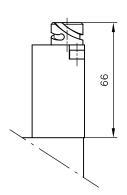
- $^{1}$ ) This dimension depends on the manufacturer and may be max. 40 mm acc. to EN 175 301-803.
- Accessories (to be ordered individually):
   SCHLEMMER-plug, 90° 10SL part No. 6217 8071-00
   SCHLEMMER-plug, straight 10SL part No. 6217 8070-00

Type PMZ 1

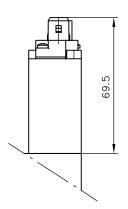
Solenoid coding S



Solenoid coding S..T



Solenoid coding AMP 24 H 4



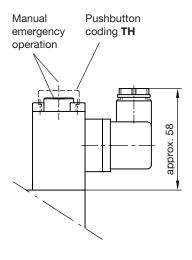
Solenoid coding G.. T

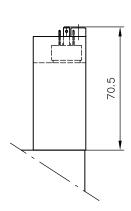
X.. TH

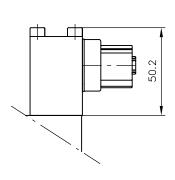
Solenoid coding G.. C 4

X.. C 4

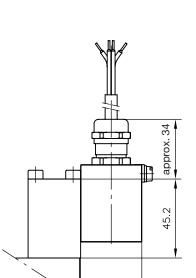
Solenoid coding DT 12 **DT 24** 





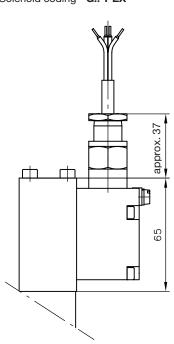


Solenoid coding G.. EX

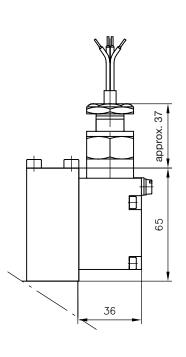


35

Solenoid coding G.. T EX



Solenoid coding G 24 MSHA

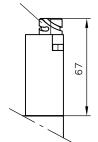


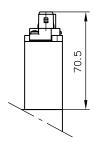
Type PMZ 01

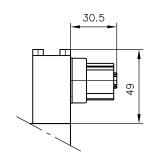
Solenoid coding \$ 12 \$ 24 Solenoid coding AMP 12 K 4 AMP 24 K 4

Solenoid coding DT 12 DT 24

Manual emergency operation

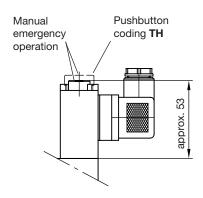


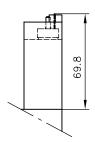




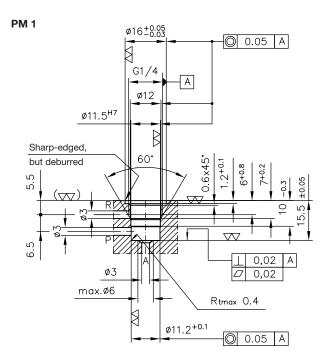
Solenoid coding G(X) 12 T G(X) 24 T

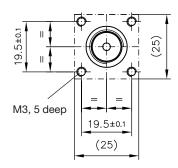
Solenoid coding G(X) 24 C 4





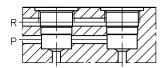
## Mounting hole



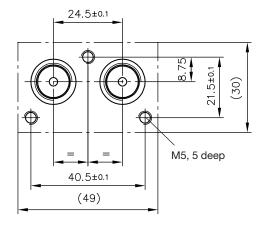


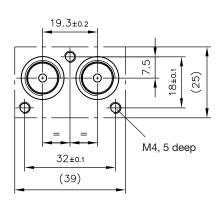
## Mounting hole

PMZ 1 PMZ 01



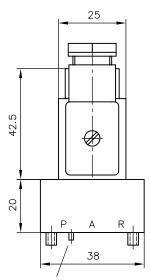
For missing dimension, see type PM 1





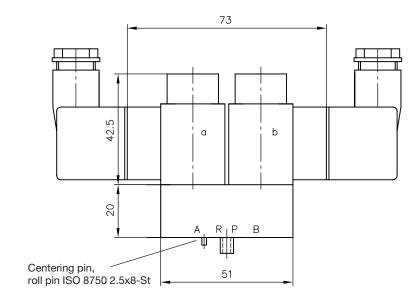
## 4.2 Version for sub-plate mounting

Individual valve type PM 11



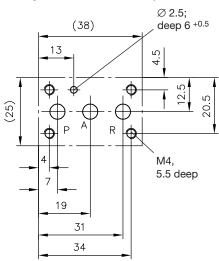
Centering pin, roll pin ISO 8750 2.5x8-St

## Double valve type PM 12

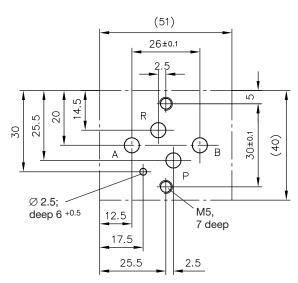


Hole pattern of the manifold (viewed from top)

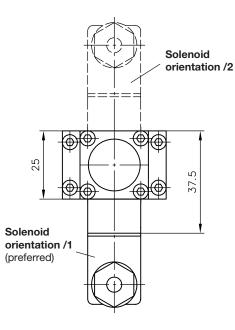
## Hole pattern of the manifold (viewed from top)

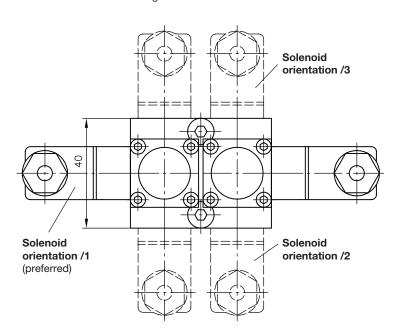


Sealing of ports A, B, P and R via O-rings 6.07x1.78 NBR 90 Sh

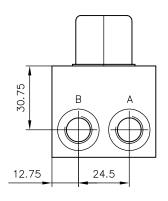


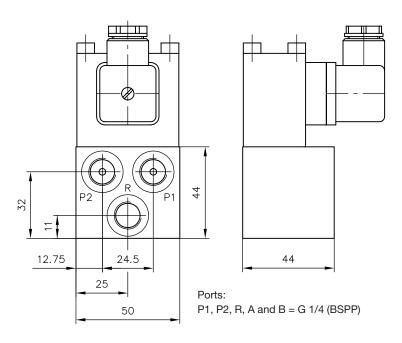
Sealing of ports A, B, P and R via O-rings 6.07x1.78 NBR 90 Sh



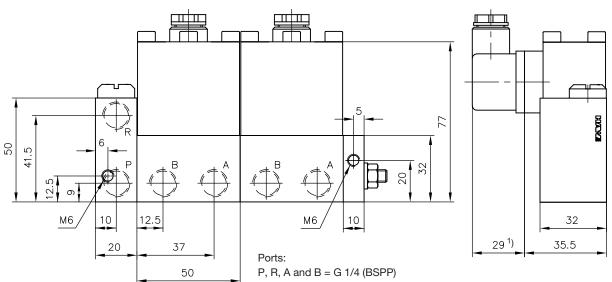


## 4.3 Versions for direct pipe connection





## 4.4 Valve bank version type PMZ



1) This dimension depends on the manufacturer and may be max. 40 mm acc. to EN 175 301-803.

## 5. Appendix

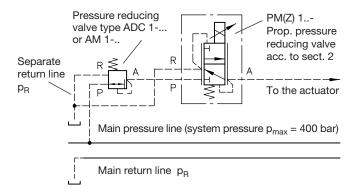
## Notes for lay-out

A pressure reducing valve type ADC 1-... or AM 1-... acc. to D 7458 should be provided upstream of the prop. pressure reducing valve to limit the pressure entering down to approx. 40, when the system pressure is between 40 and  $p_{max} = 400$  bar.

## Case 1:

Joined, depressurized return for control and return oil from the piloting and prop. pressure reducing valve via separate line.

This way the influence of  $p_R$  in the return line can be neglected and will show no influence on the characteristic of the valve i.e. pressure  $p_A$ .



## Case 2:

All control and return oil from the piloting and prop. pressure reducing valve is fed into the system return line. Drawback is that the varying system return pressure  $p_{\text{R}}$  shows a significant influence on the characteristic of the valve i.e. pressure  $p_{\text{A}}.$  This negative influence can be prevented by compensation via a connection between system return line and the rear cavity of the actuator.

